

# Markov Chains I

Lec.26

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# Markov Chains: Fundamental Idea

We now wish to model sequences of random variables

$X_0, X_1, X_2, \dots$ . You can think of  $X_n$  as the state of a system at time  $n$ .  
*↪ not iid., but the values that they take on all come from  $\mathcal{X}$*

We will be working on the setting where time is discrete, and each  $X_i$  can only take on a finite set of values. This finite set of values is denoted  $\mathcal{X}$  and is called the state space.

# Markov Property

Think of  $X_n$  be the present/current state, and  $X_{n+1}$  as the future state. The Markov Property is:

$$\Pr(\underbrace{X_{n+1} = j}_{X_{n+1}} | \underbrace{X_n = i, \dots, X_0 = i_0}_{X_0, \dots, X_n}) = \Pr(X_{n+1} = j | \underbrace{X_n = i}_{X_n})$$

This property is not saying the future is independent of the past.  
This property is saying that the past and future are conditionally independent given the present.

Note:

time  $n$  is missing

We call  $\Pr(X_{n+1} = j | X_n = i) = \underbrace{P(i, j)}_{P(i, j)}$  the transition probability from state  $i$  to state  $j$ .

In this class, we will only deal with time homogeneous Markov chains.

# Transition Probability Matrix

Let the state space  $\mathcal{X}$  be  $\{1, \dots, k\}$ . The transition probability matrix for a Markov chain  $P$  is a  $k$  by  $k$  matrix such that the entry in the  $i$ th row and  $j$  column is  $P(i, j)$ , and:

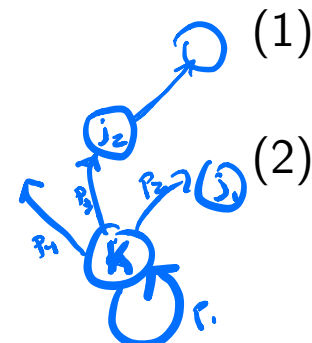
the prob. of going from state  $i$  to state  $j$  in 1 step

$$P(i, j) \geq 0 \quad \forall i, j \in \mathcal{X} \quad (1)$$

" the rows of  $P$  sum to 1 "  $\rightarrow \sum_{j=1}^k P(i, j) = 1 \quad \forall i \in \mathcal{X}$

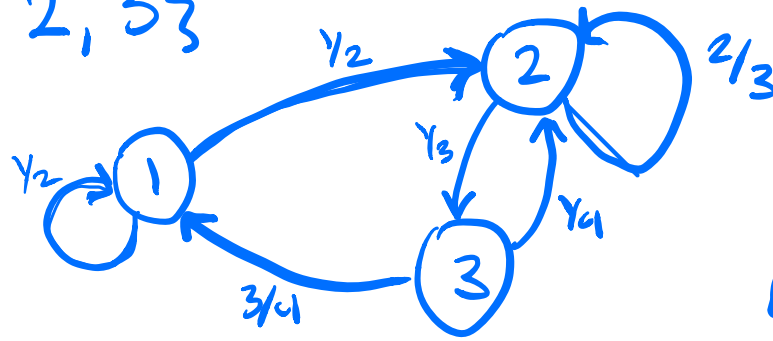
" the probability of going somewhere is 1 "

Note:  $P(i, i)$  is valid (you can go from a state back to the same state)



# Markov Chain Example

$$\mathcal{X} = \{1, 2, 3\}$$



$$x_0, x_1, x_2, \dots, x_n, \dots$$

$$\pi_0(1) = 1$$

Potential initial distribution

$$\pi_0 = [1 \ 0 \ 0]$$

$$\rightarrow \pi_0 = [1/3 \ 1/3 \ 1/3]$$

$$\downarrow \pi_0(1) = 1/3 \quad \vdots$$

$$P = \begin{bmatrix} 1/2 & 1/2 & 0 \\ 0 & 2/3 & 1/3 \\ 3/4 & 1/4 & 0 \end{bmatrix}$$

$i$ th row  $j$ th column  
is the probability  
of going from state  $i$   
to state  $j$  in one  
timestep.

Ex:  $\pi_0 = [1 \ 0 \ 0]$

$$\pi_1 = \pi_0 P = [1 \ 0 \ 0] \begin{bmatrix} 1/2 & 1/2 & 0 \\ 0 & 2/3 & 1/3 \\ 3/4 & 1/4 & 0 \end{bmatrix} = [1/2 \ 1/2 \ 0]$$

# Distribution Over States

If there are  $K$  states,  $\pi_i$  is a  $1 \times K$  row vector.

We use  $\pi_i$  to represent the distribution of our random variable  $X_i$  over the states in  $\mathcal{X}$ . The entries in  $\pi_i$  must be probabilities that sum up to 1.

$\pi_0$  is called our initial distribution.  $\pi_0$ , in conjunction with  $P$  and  $\mathcal{X}$  fully specifies our Markov chain.

$$\pi_n(i) = P(X_n = i), \text{ where } i \in \mathcal{X}$$

# Moving in Time

Suppose at time  $n$ ,  $X_n$  has distribution  $\pi_n$ . Then, by the Law of Total Probability,

$$\Pr(X_{n+1} = j) = \sum_i \Pr(X_{n+1} = j | X_n = i) \Pr(X_n = i) \quad (3)$$

$\Pr(X_{n+1} = j \wedge X_n = i)$

$$= \sum_i P(i, j) \pi_n(i) \quad (4)$$

$(1 \times k) \cdot (k \times k) = 1 \times k$

But  $\sum_i P(i, j) \pi_n(i)$  is the  $j$ th entry of  $\pi_n P$ . So,

$$\pi_1 = \pi_0 P$$

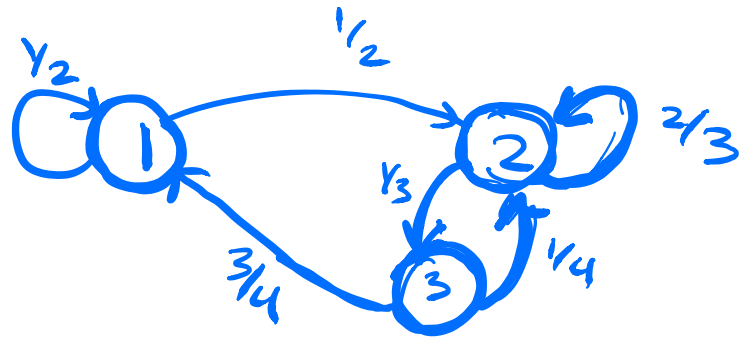
$$\pi_{n+1} = \pi_n P \quad (5)$$

$$\pi_{n+2} = \pi_{n+1} P = \pi_n P P = \pi_n P^2 \quad (6)$$

$P^k$  is the probability transition matrix where the entry in the  $i$ th row  $j$ th column is the probability of going from state  $i$  to state  $j$  in  $k$  steps.

# Hitting Time Example

What is the average number of steps it takes to reach state 1 starting at state 2?



Let  $B(i)$  denote the average # of steps needed to reach state 1 starting from state  $i$ .

Then,  $B(1) = 0$

$$B(3) = 1 + \frac{3}{4} \cdot B(1) + \frac{1}{4} \cdot B(2)$$

$$B(2) = 1 + \frac{2}{3} \cdot B(2) + \frac{1}{3} \cdot B(3)$$

3 eqns, 3 variables.

Solve  $\Rightarrow$

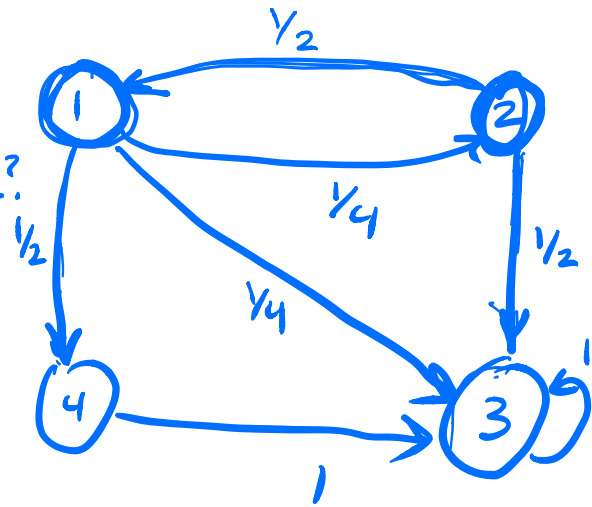
$$\begin{aligned} B(1) &= 0 \\ B(2) &= \frac{16}{3} \\ B(3) &= \frac{7}{3} \end{aligned}$$



# Probability of A before B Example

What is the probability of reaching state 3 before state 4, starting from state 1?

Let  $\alpha(i)$  be the probability of reaching state 3 before state 4, starting from state  $i$



Then,  $\alpha(3) = 1$

$$\alpha(4) = 0$$

$$\alpha(2) = \frac{1}{2} \cdot \alpha(1) + \frac{1}{2} \cdot \alpha(3)$$

$$\alpha(1) = \frac{1}{2} \alpha(4) + \frac{1}{4} \alpha(3) + \frac{1}{4} \alpha(2)$$

4 eqn. 4 variables.  
solve  $\Rightarrow$

$$\alpha(3) = 1$$

$$\alpha(4) = 0$$

$$\alpha(2) = \frac{10}{14}$$

$$\alpha(1) = \frac{3}{7}$$

$$P = \begin{bmatrix} 0 & \frac{1}{4} & \frac{1}{4} & \frac{1}{2} \\ \frac{1}{2} & 0 & \frac{1}{2} & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 1 & 0 \end{bmatrix}$$

# Invariant Distribution Definition

"steady state" distribution  
"stationary" distribution.

A distribution  $\pi$  is *invariant* for the transition probability matrix  $P$  if it satisfies the following *balance equations*:

$$\pi = \pi P \quad (7)$$

# Stationary Distribution Existence



Let  $P$  be the probability transition matrix for a Markov chain.

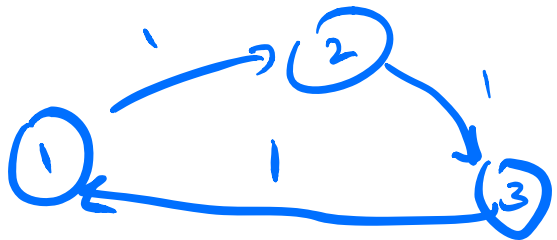
The rows of  $P$  add up to 1. Let  $\mathbf{1}$  be a column vector of ones. This means  $P\mathbf{1} = \mathbf{1} = 1 \cdot \mathbf{1}$ .

This means  $P$  has a right eigenvector corresponding to eigenvalue 1. Since the right and left eigenvalues of a square matrix are the same, this means there exists some left eigenvector  $\pi$  such that  $\pi P = 1 \cdot \pi$ .

Note that this does not say anything about the uniqueness of the stationary distribution.

"stationary disto is a left eigenvector of P  
w/ eigenvalue 1"

# Stationary Distribution Example



$$P = \begin{bmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \\ 1 & 0 & 0 \end{bmatrix}$$

$$\pi = \pi P$$

balance eqns.

$$[\pi(1) \ \pi(2) \ \pi(3)] = [\pi(1) \ \pi(2) \ \pi(3)] \begin{bmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \\ 1 & 0 & 0 \end{bmatrix}$$

in dep. need 1 more eqn.

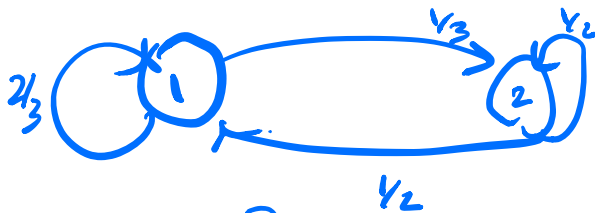
$$\begin{cases} \pi(1) = \pi(3) \\ \pi(2) = \pi(1) \\ \pi(3) = \pi(2) \end{cases}$$

replace an eqn. w/

$$\pi(1) + \pi(2) + \pi(3) = 1$$

$$\Rightarrow \begin{aligned} \pi(1) &= 1/3 \\ \pi(2) &= 1/3 \\ \pi(3) &= 1/3 \end{aligned}$$

$$\pi = [1/3 \ 1/3 \ 1/3]$$



$$P = \begin{bmatrix} 2/3 & 1/3 \\ 1/2 & 1/2 \end{bmatrix}$$

$$\pi = \pi P$$

$$[\pi(1) \ \pi(2)] = [\pi(1) \ \pi(2)] \begin{bmatrix} 2/3 & 1/3 \\ 1/2 & 1/2 \end{bmatrix}$$

dep.

$$\begin{cases} \pi(1) = \pi(1) \cdot 2/3 + \pi(2) \cdot 1/2 \\ \pi(2) = \pi(1) \cdot 1/3 + \pi(2) \cdot 1/2 \end{cases}$$

replace an eqn w/

$$\pi(1) + \pi(2) = 1$$

$$\Rightarrow \begin{aligned} \pi(1) &= 3/5 \\ \pi(2) &= 2/5 \end{aligned}$$

